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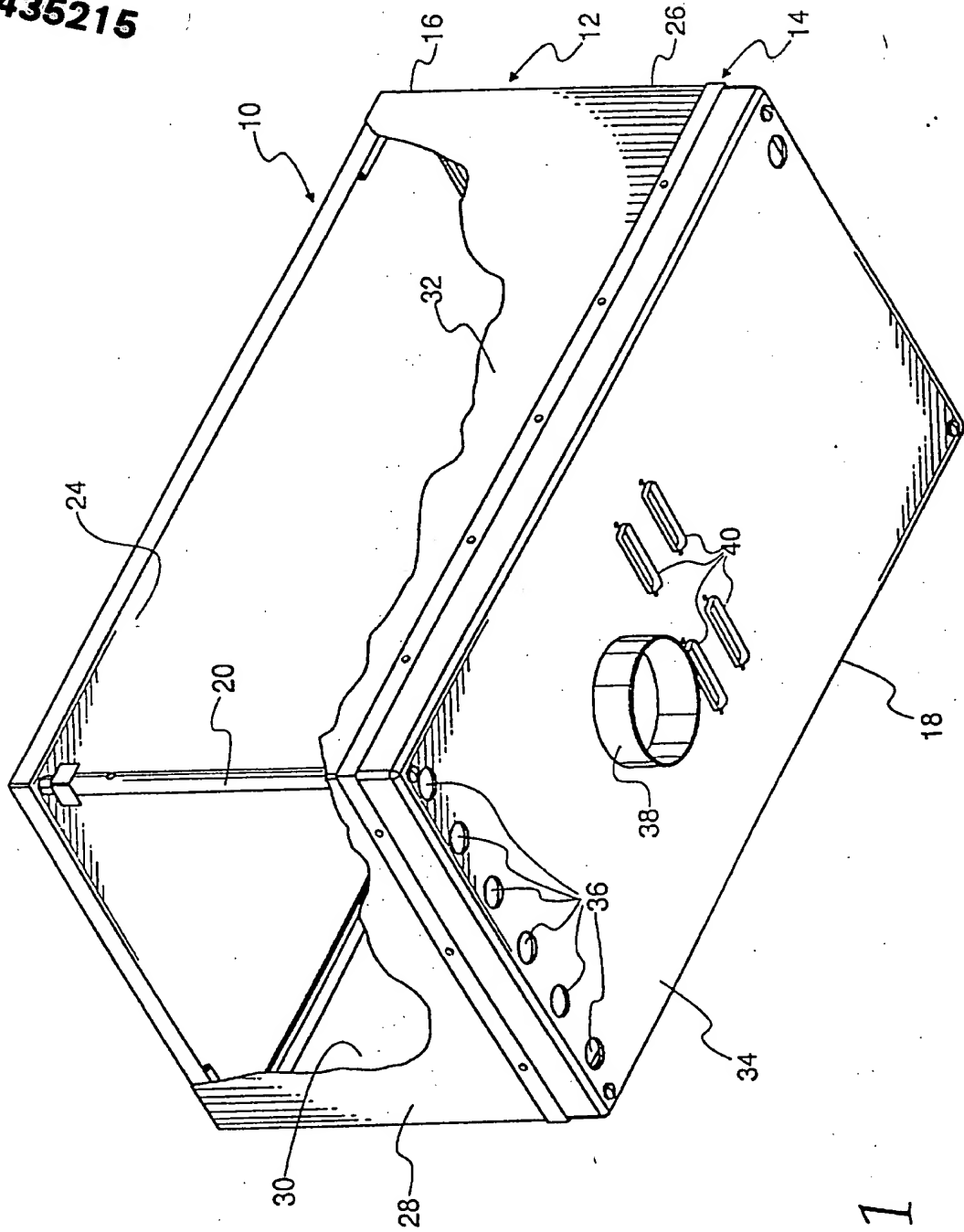


Fig. 1

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FIG. 2

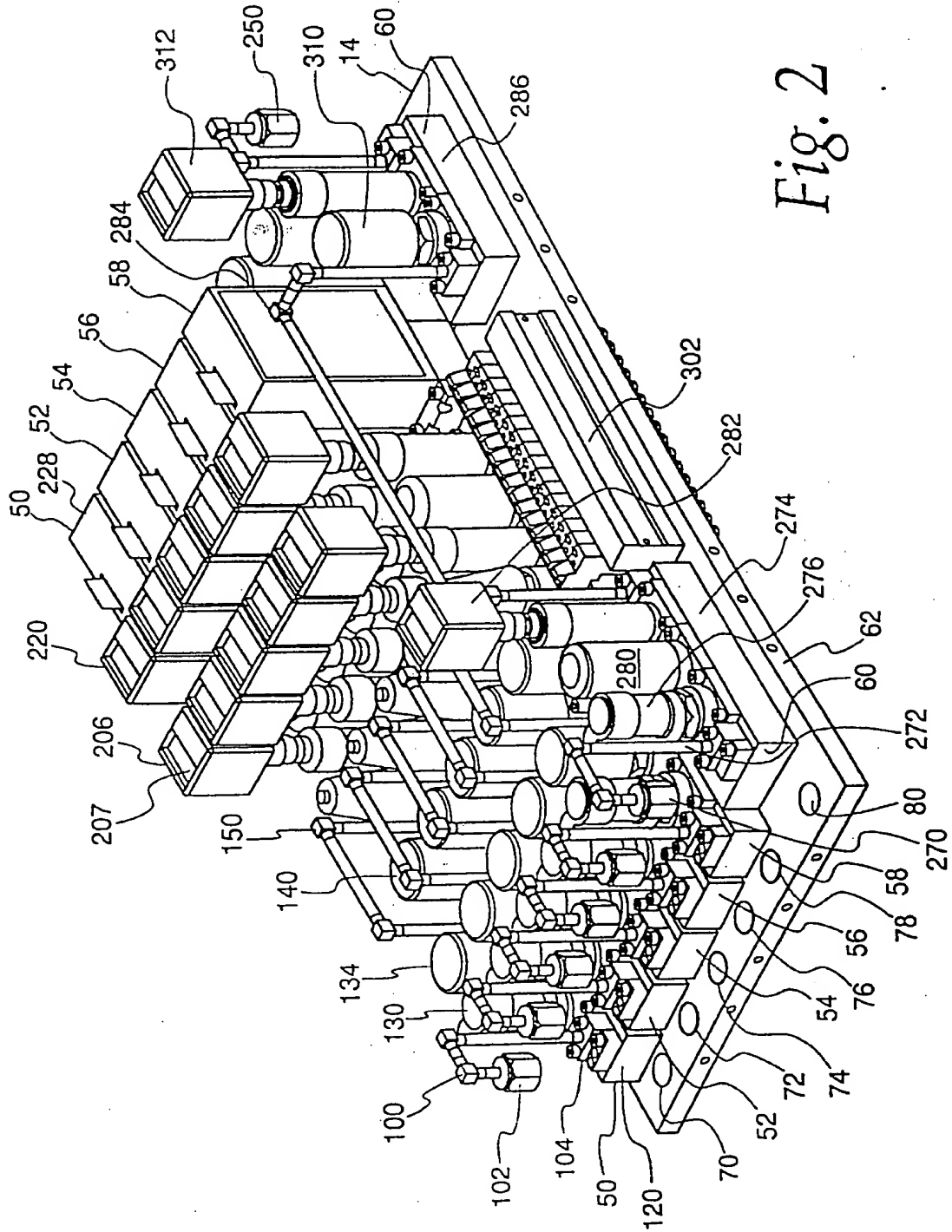


Fig. 2

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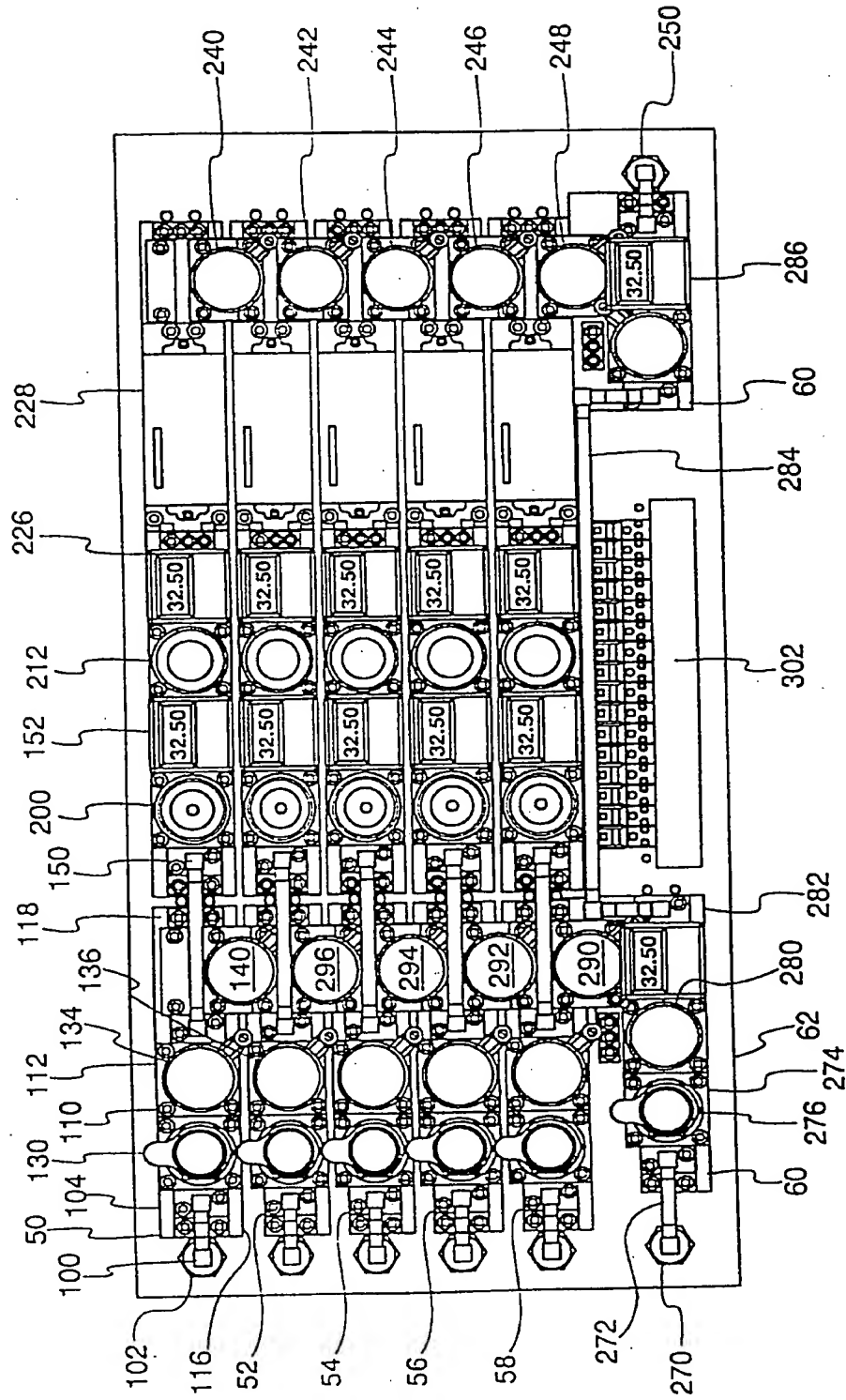
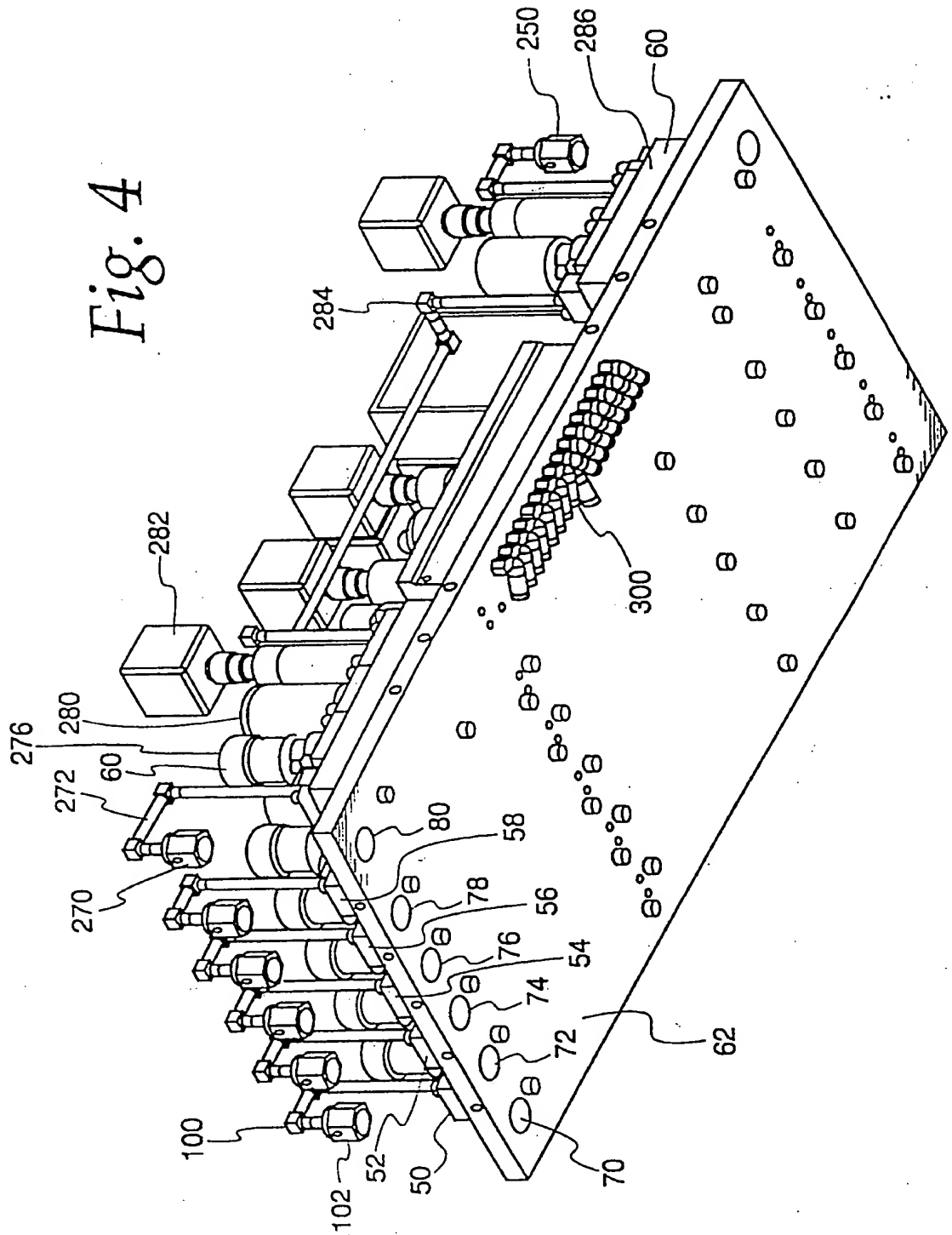


Fig. 3

Fig. 4



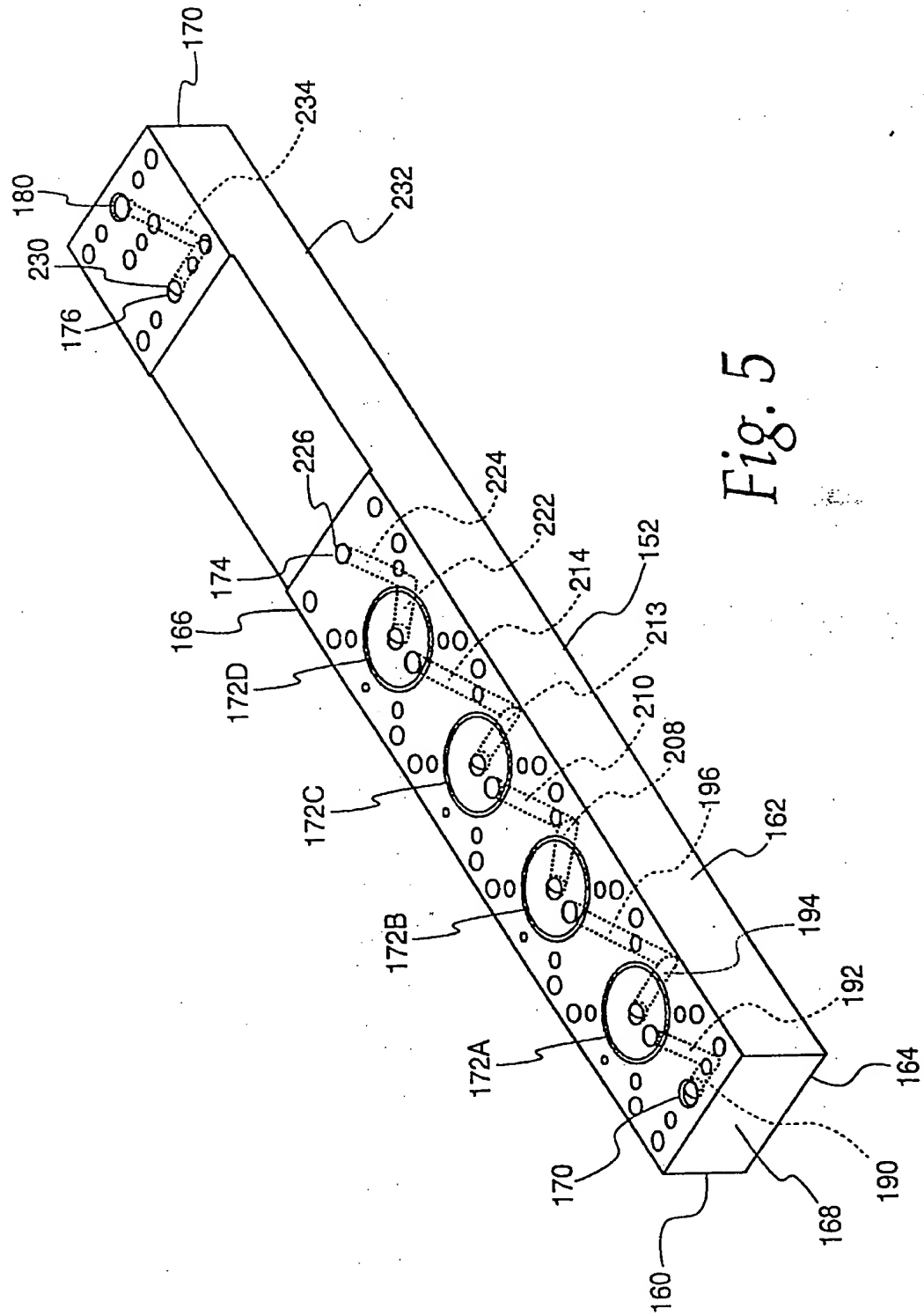


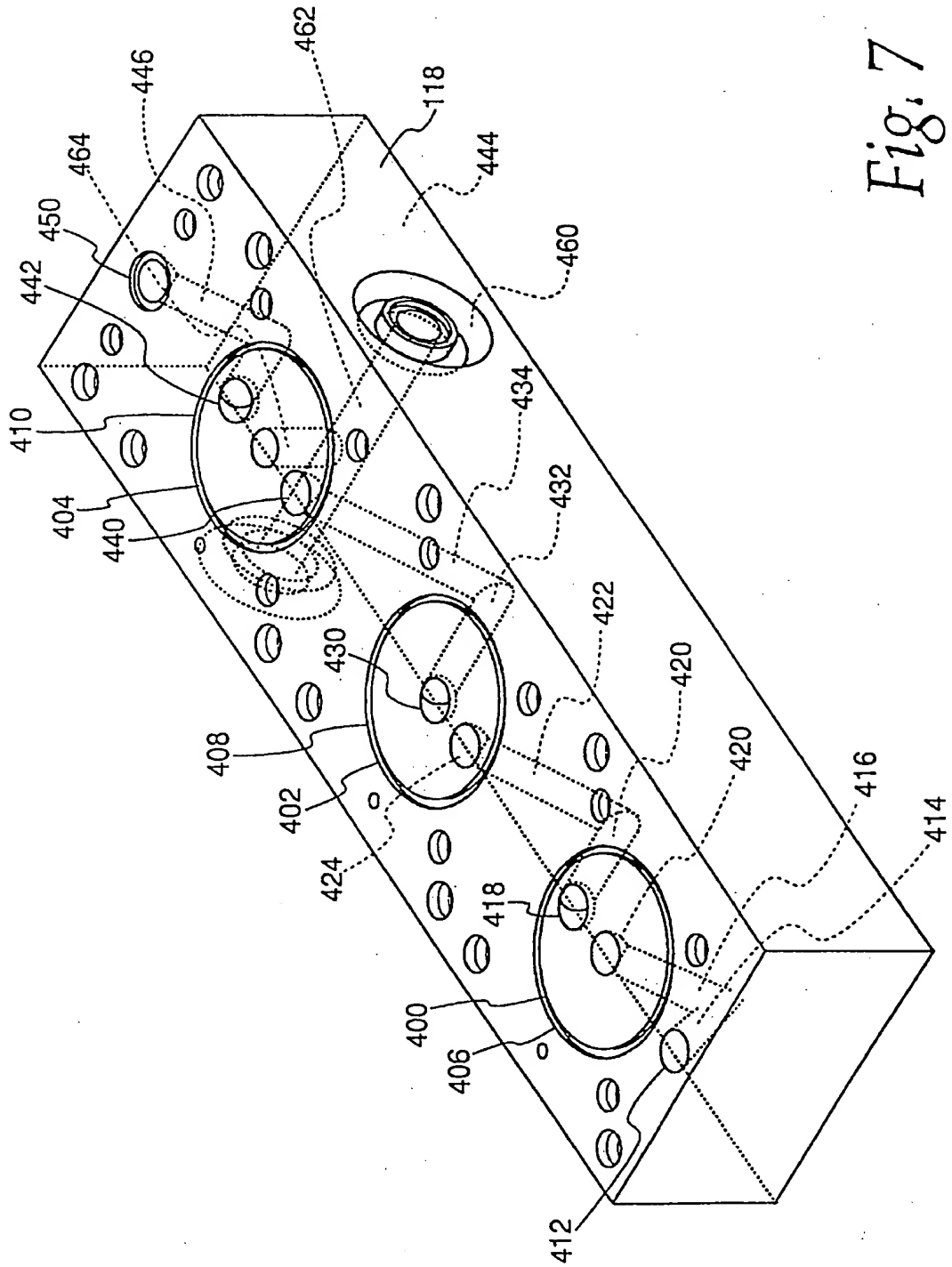
Fig. 5

FIG. 5



Fig. 6

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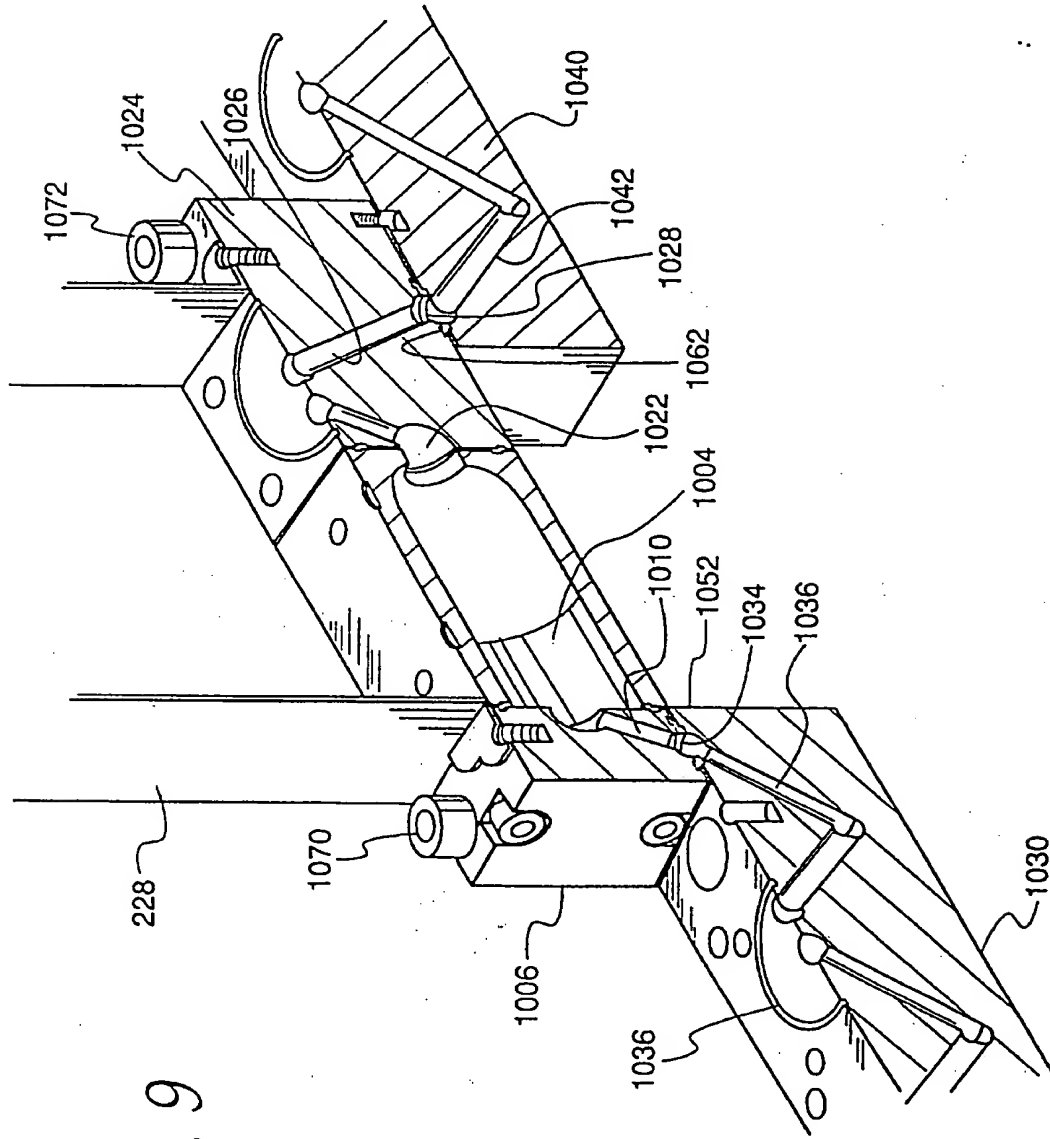
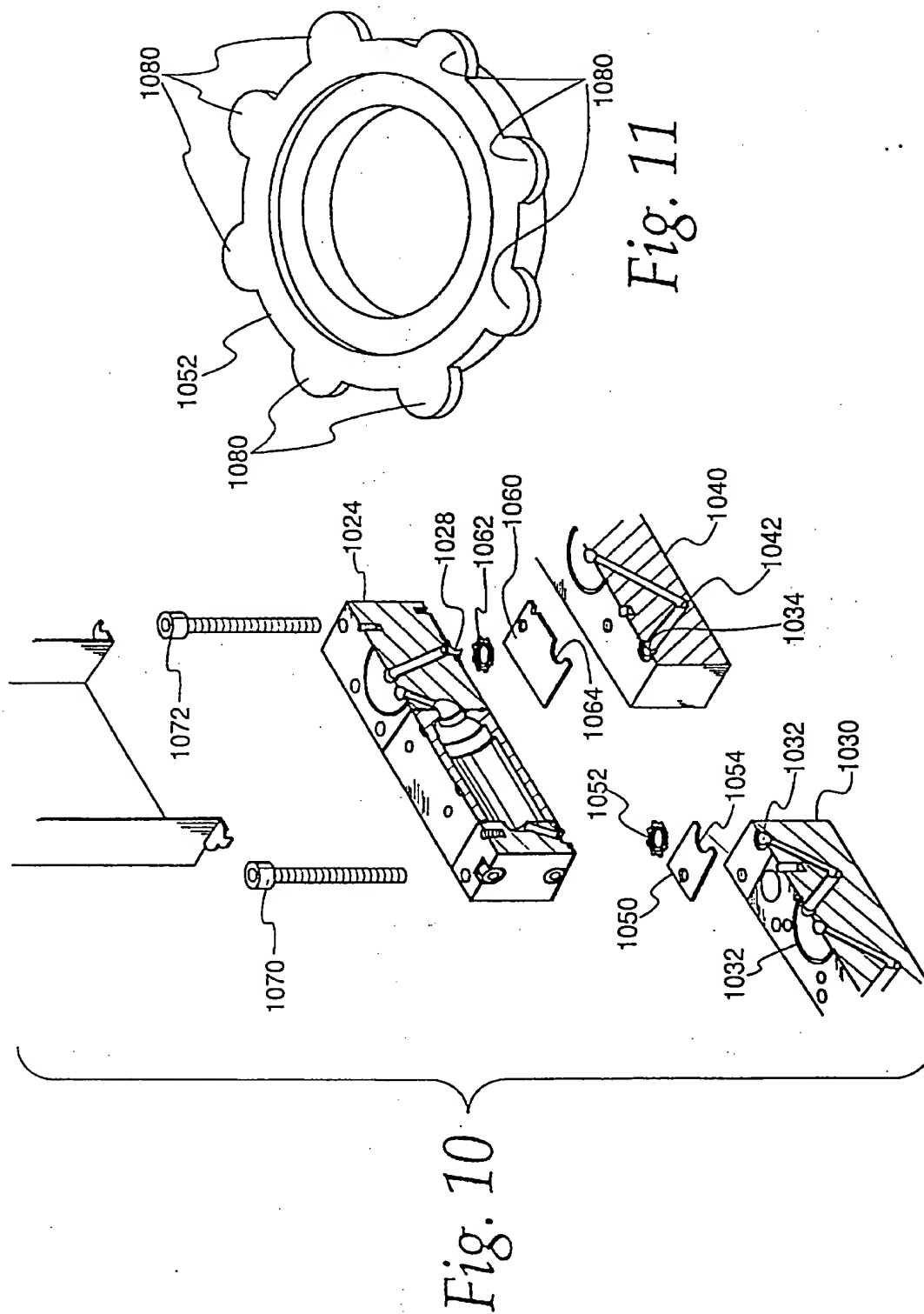
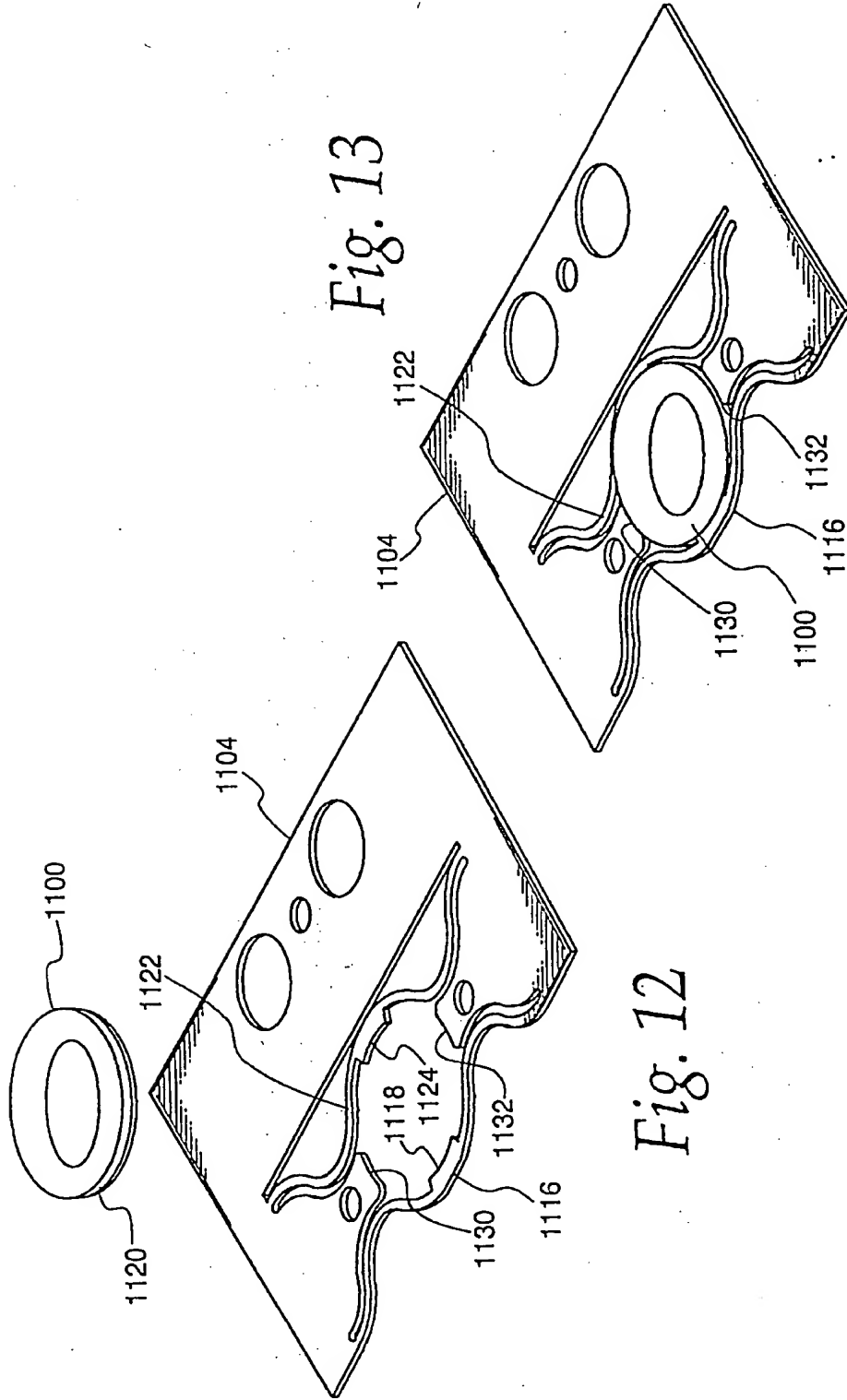


Fig. 9





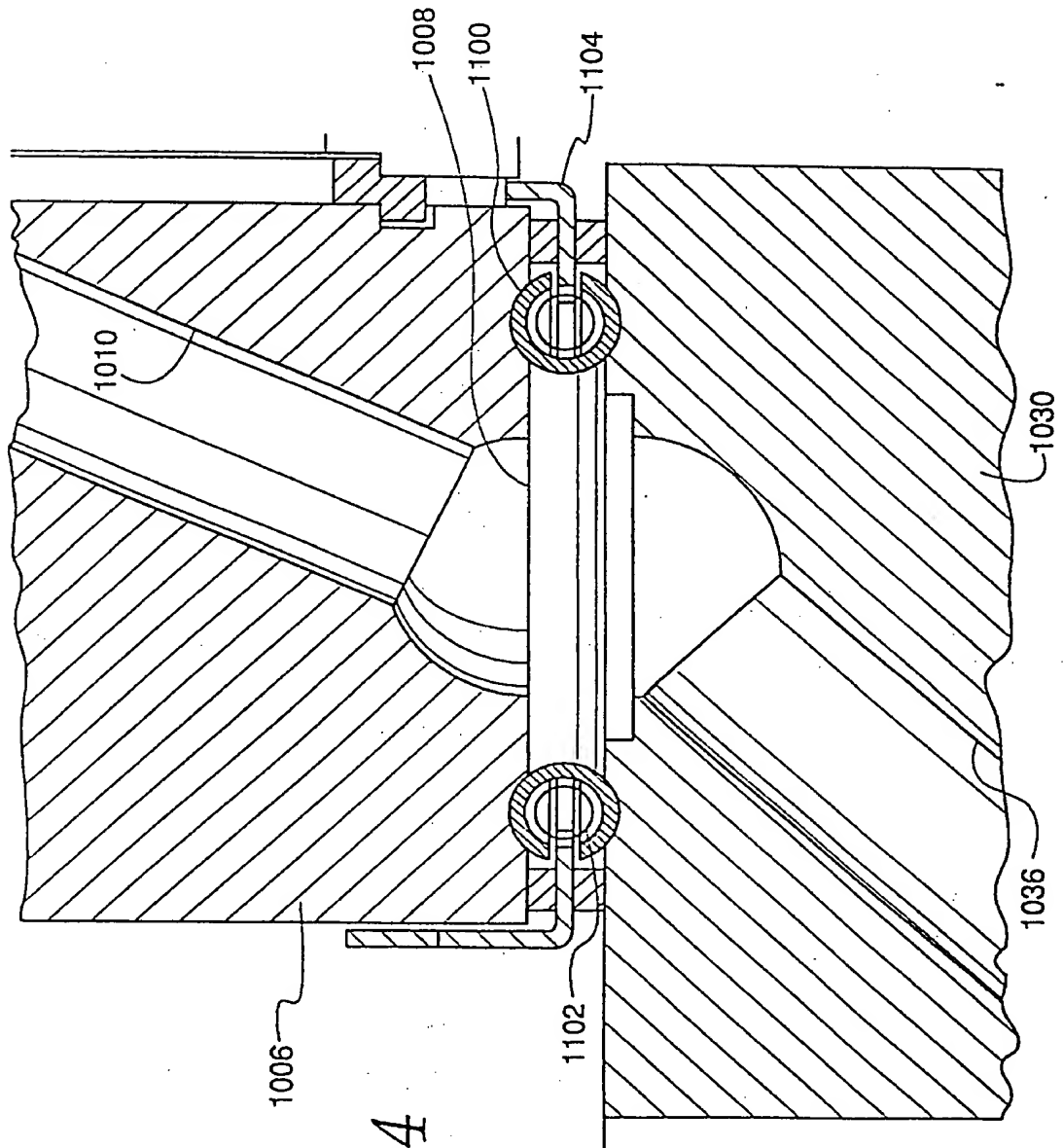


Fig. 14

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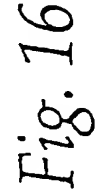
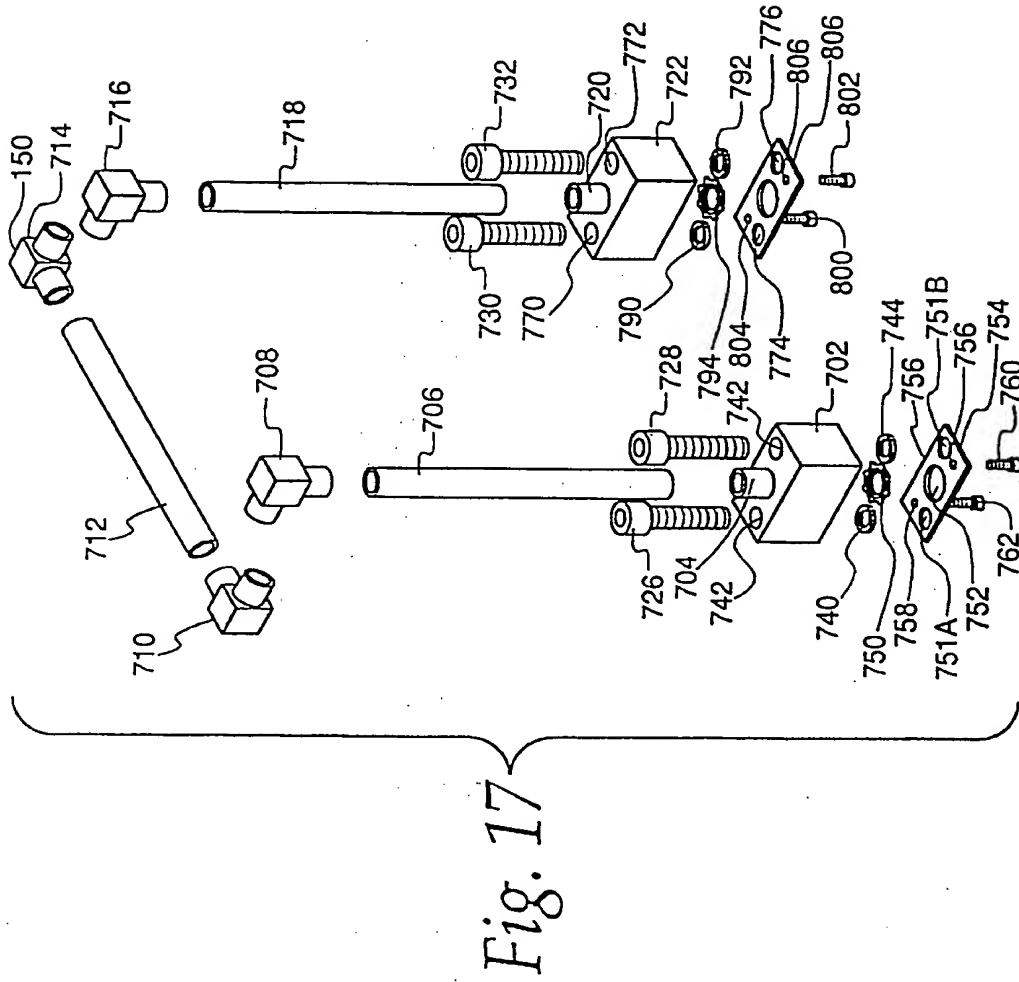


FIG. 17



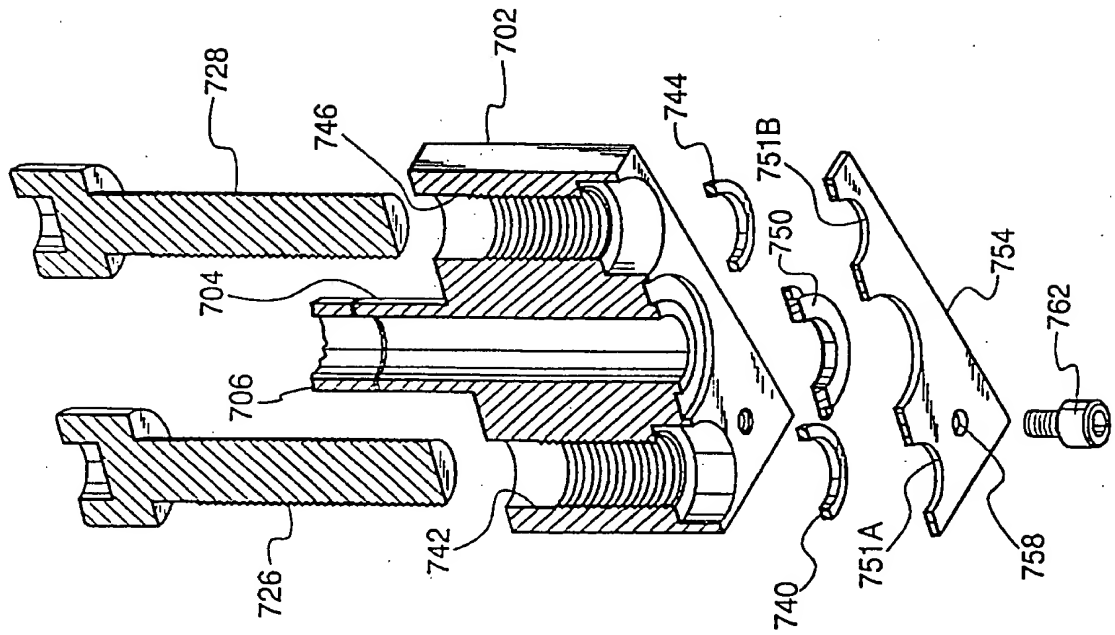


Fig. 18

FIG. 18

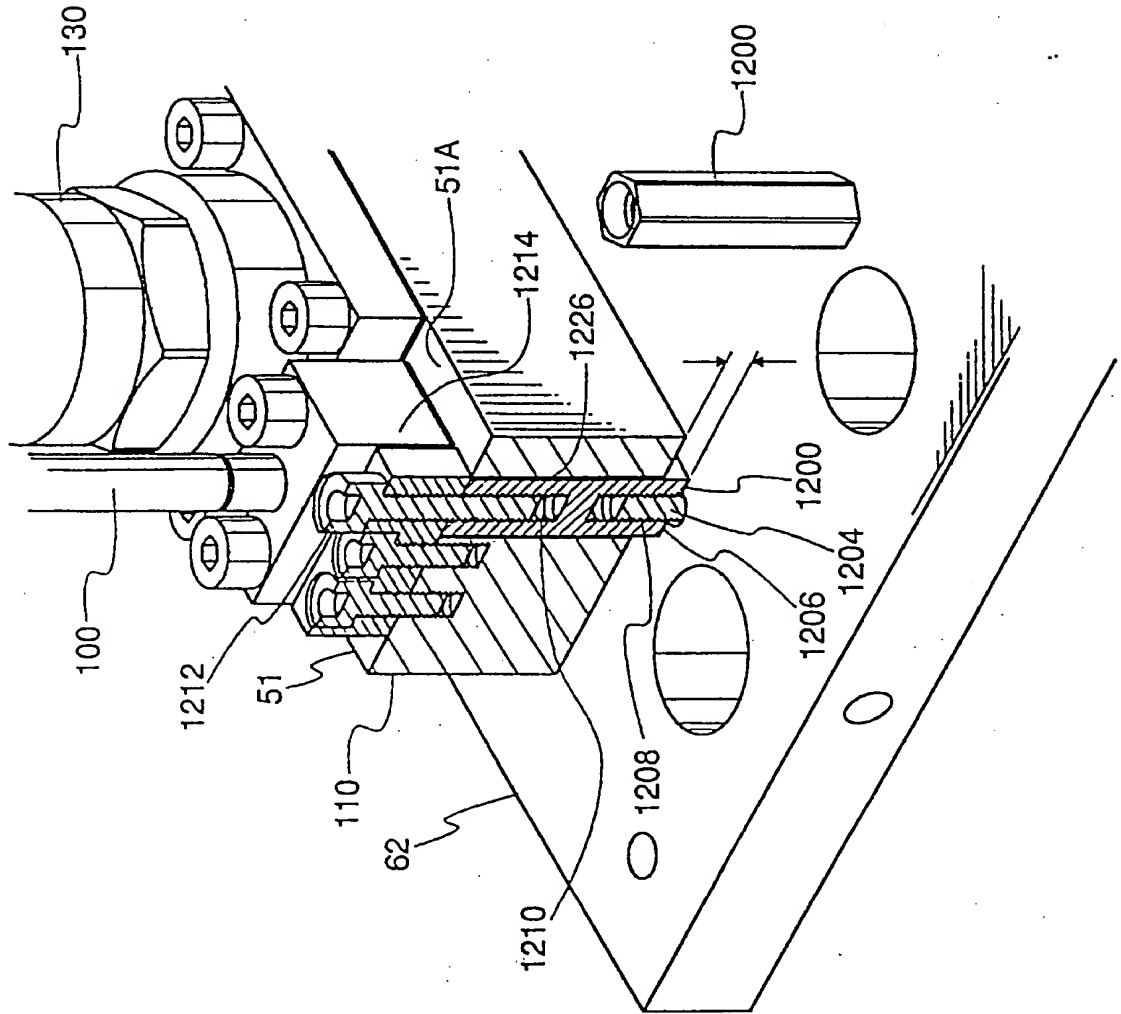


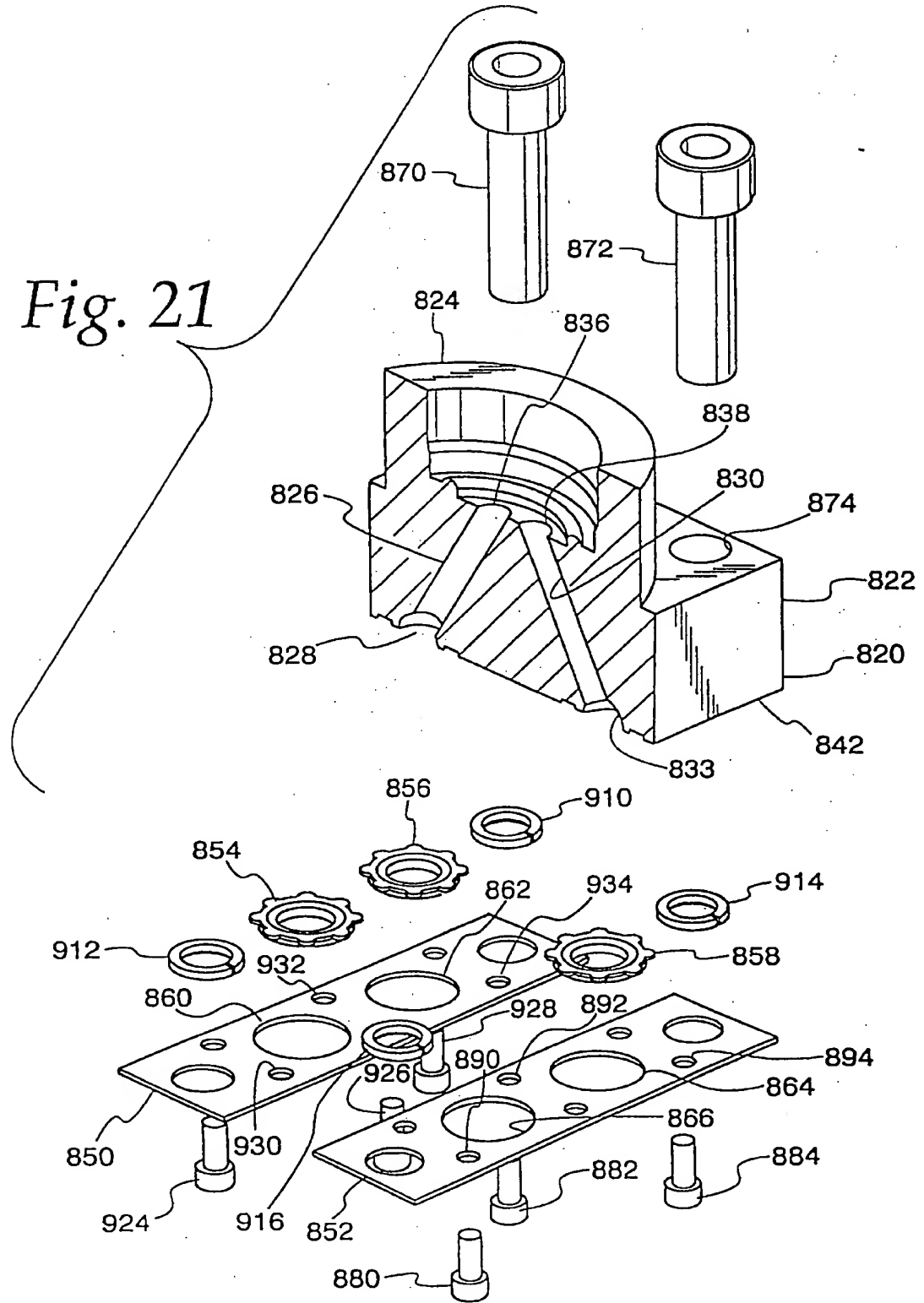
Fig. 19

FIG. 19



Fig. 20 is a perspective view of a mechanical assembly, likely a robotic arm or a similar articulated structure. The assembly consists of several interconnected components, including a base (1302), a main body (1304), and a distal end (1306). The assembly is shown in a partially extended position, with various joints and components labeled with reference numerals. Key components include: 1302 (base), 1304 (main body), 1306 (distal end), 1308 (joint), 1310 (link), 1312 (joint), 1314 (link), 1316 (joint), 1318 (link), 1320 (joint), 1322 (link), 1324 (joint), 1326 (link), 1328 (joint), 1330 (link), 1332 (joint), 1334 (link), 1336 (joint), 1338 (link), 1340 (joint), 1342 (link), 1344 (joint), 1346 (link), 1348 (joint), 1350 (link), 1352 (joint), 1354 (link), 1356 (joint), 1358 (link), 1360 (joint), 1362 (link), 1364 (joint), 1366 (link), 1368 (joint), 1370 (link), 1372 (joint), 1374 (link), 1376 (joint), 1378 (link), 1380 (joint), 1382 (link), 1384 (joint), 1386 (link), 1388 (joint), and 1390 (link).

Fig. 21



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FIG. 22

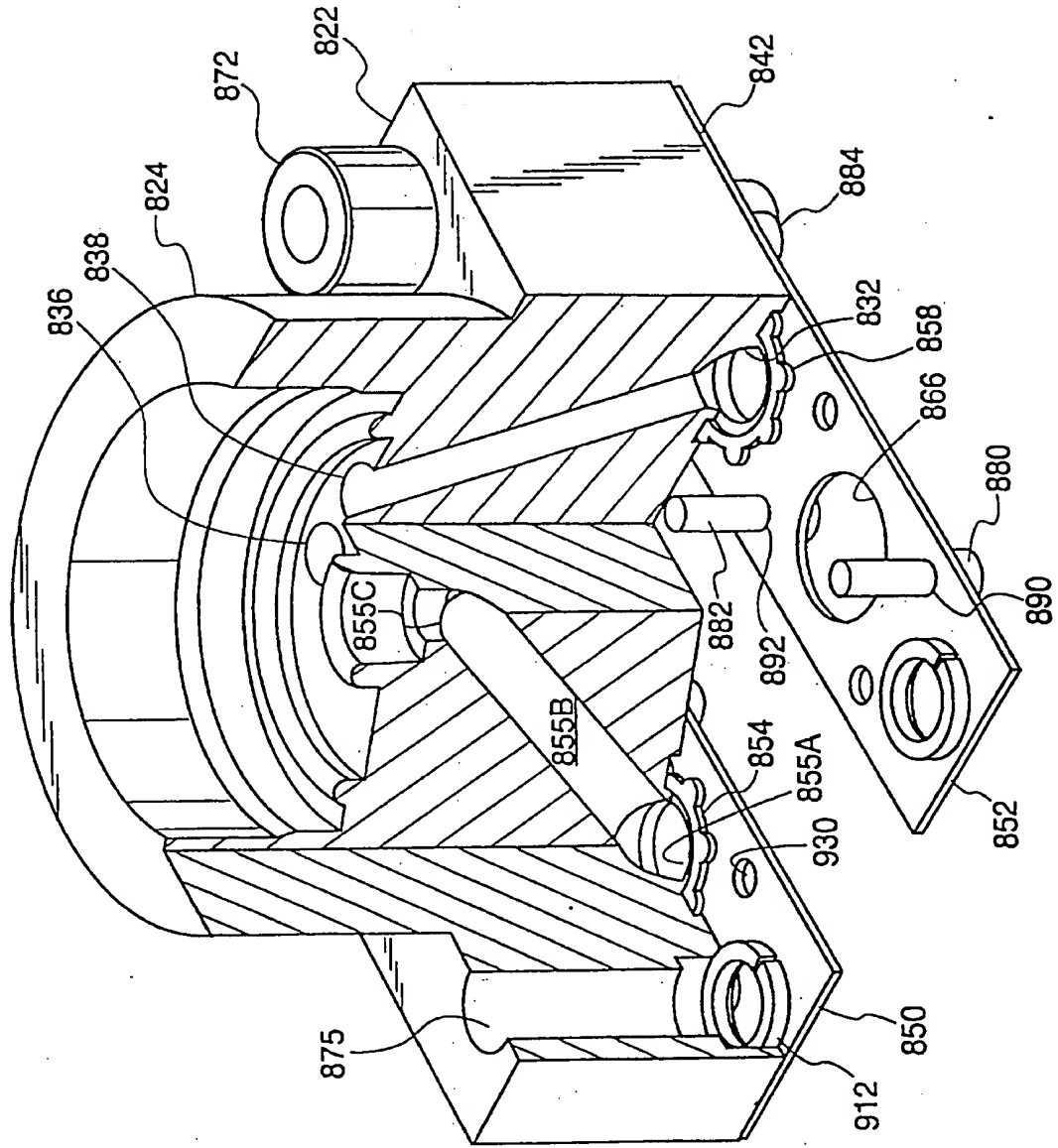


FIG. 23

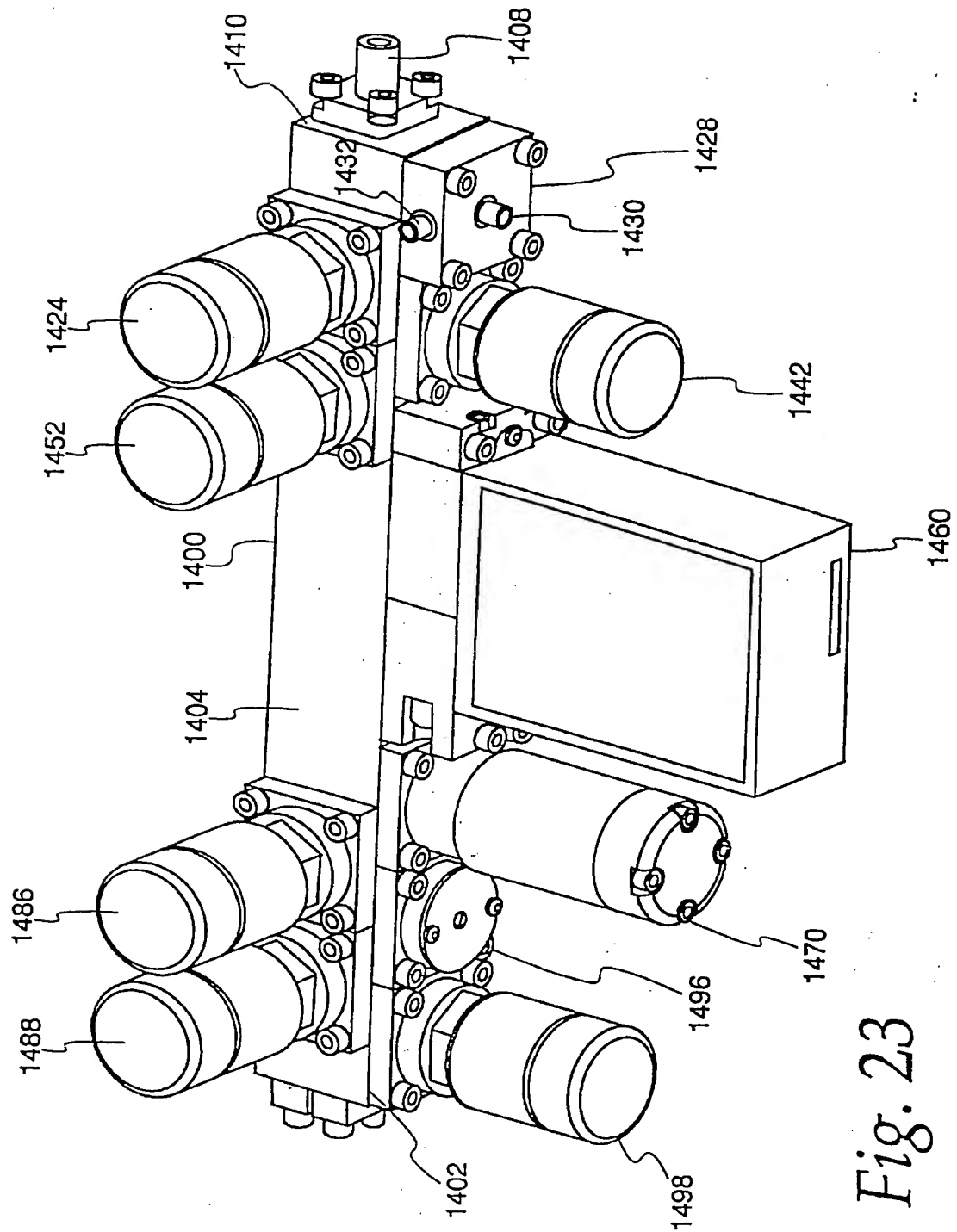
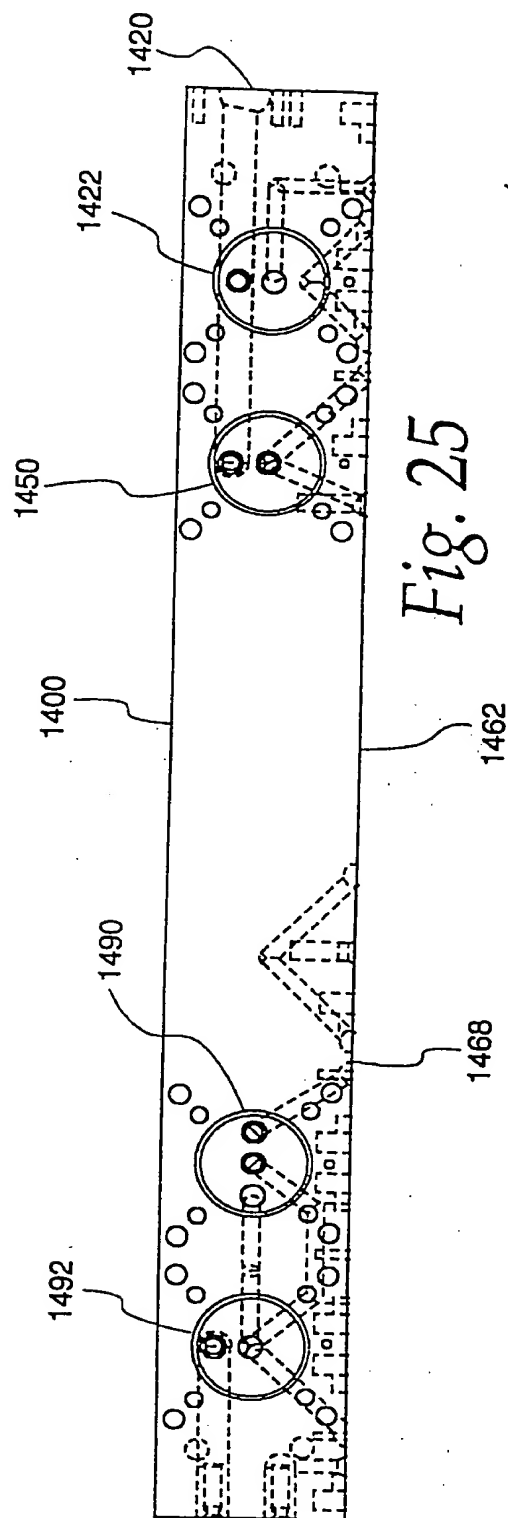
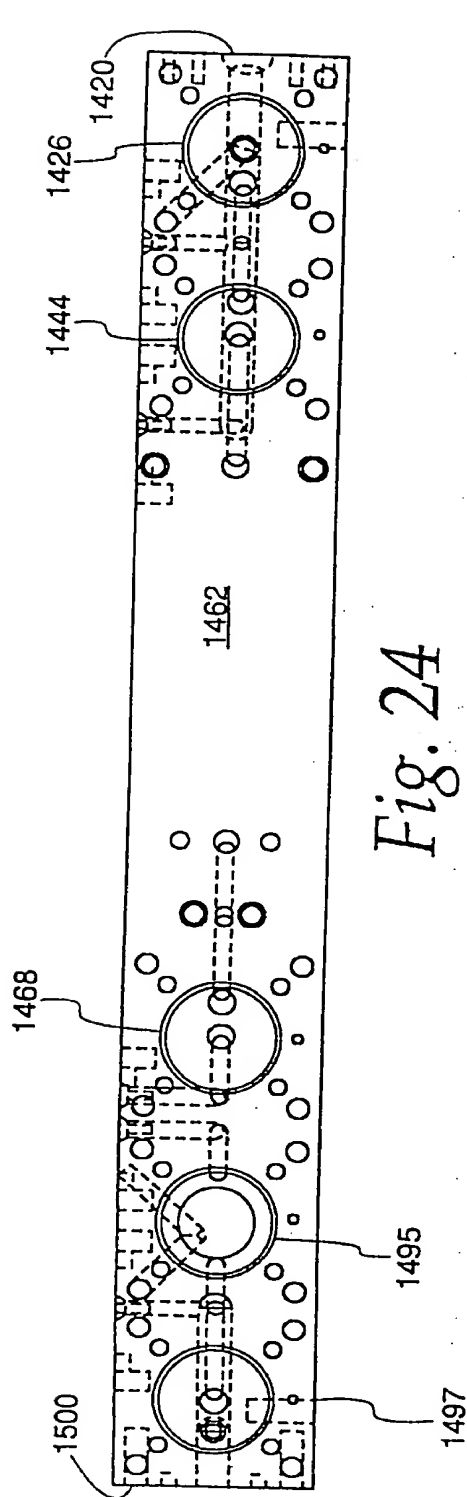


Fig. 23



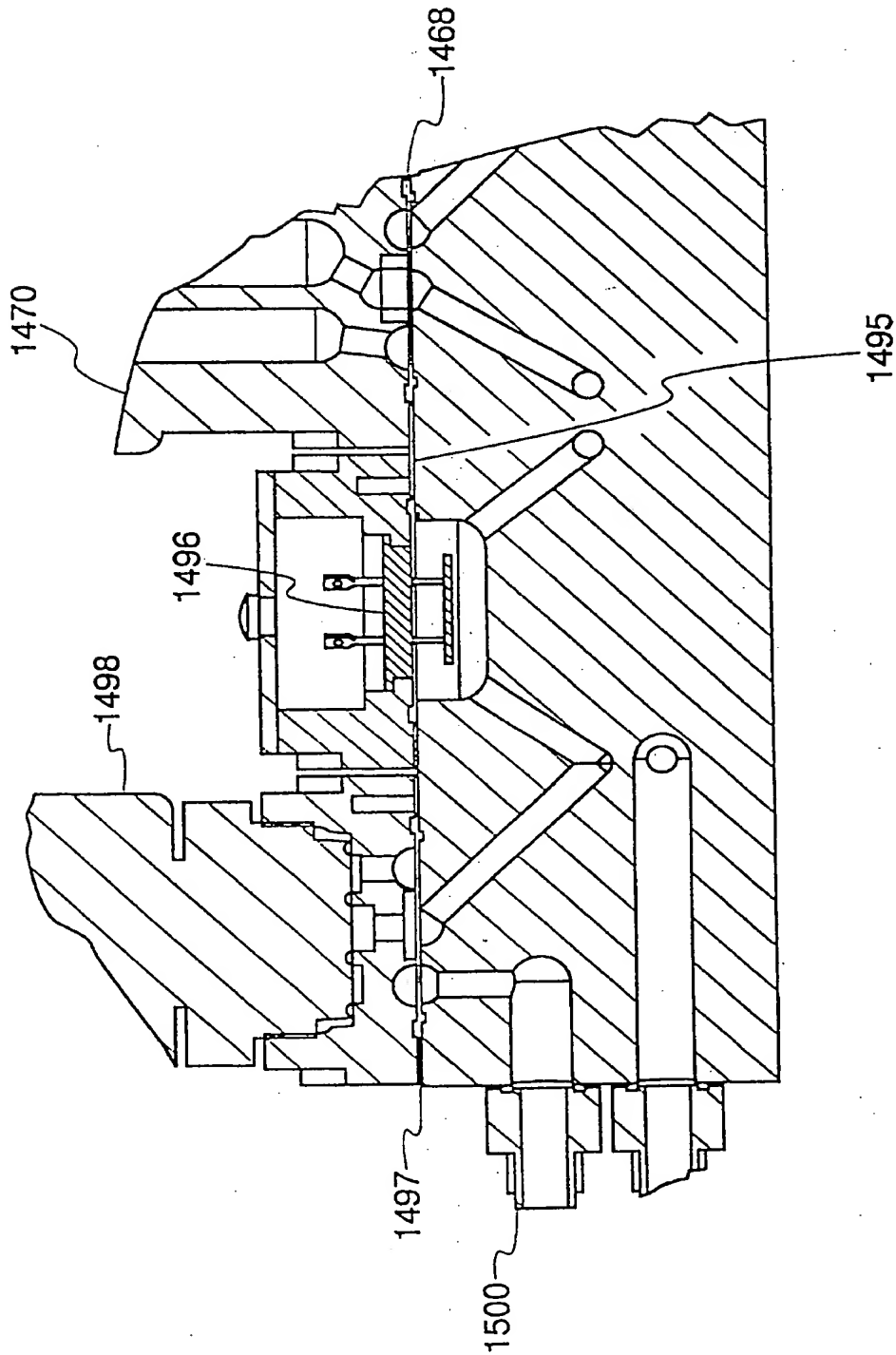


Fig. 26

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